



Steven Hudson
August 21, 2013

A New Method for Detecting Bearing Wear in Slow Speed Machines



Warning – Technical Content *

Window Factor

$$\#FFT\ Lines = \frac{\# Samples}{2.56}$$

Anti – Aliasing

Nyquist Criterion

$$DAT = \frac{\# FFT\ Lines}{F_{max}}$$

DownSampling

*** If These Expressions Are Not Familiar To You Then
The Following Content My Not Be Suitable**

Slow Speed Machines





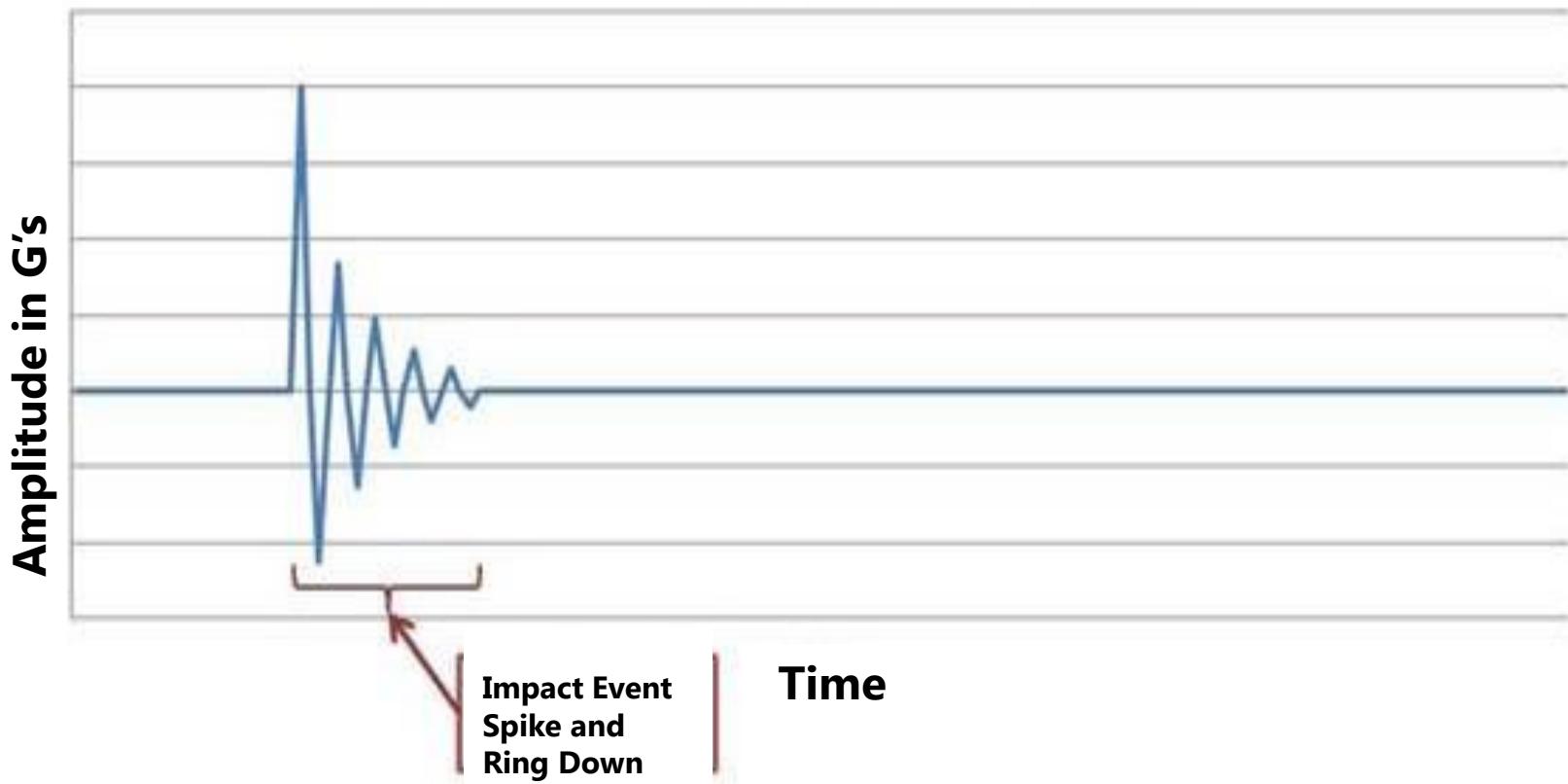
Impact Demod

- **Impact signals** in machinery
- **Impact detection difficulties** in slow speed machines
- **Legacy Demodulation** ineffectiveness
- **Impact Demod functionality**
- Impact Demod **setup and analysis tips**
- Impact Demod **in action**

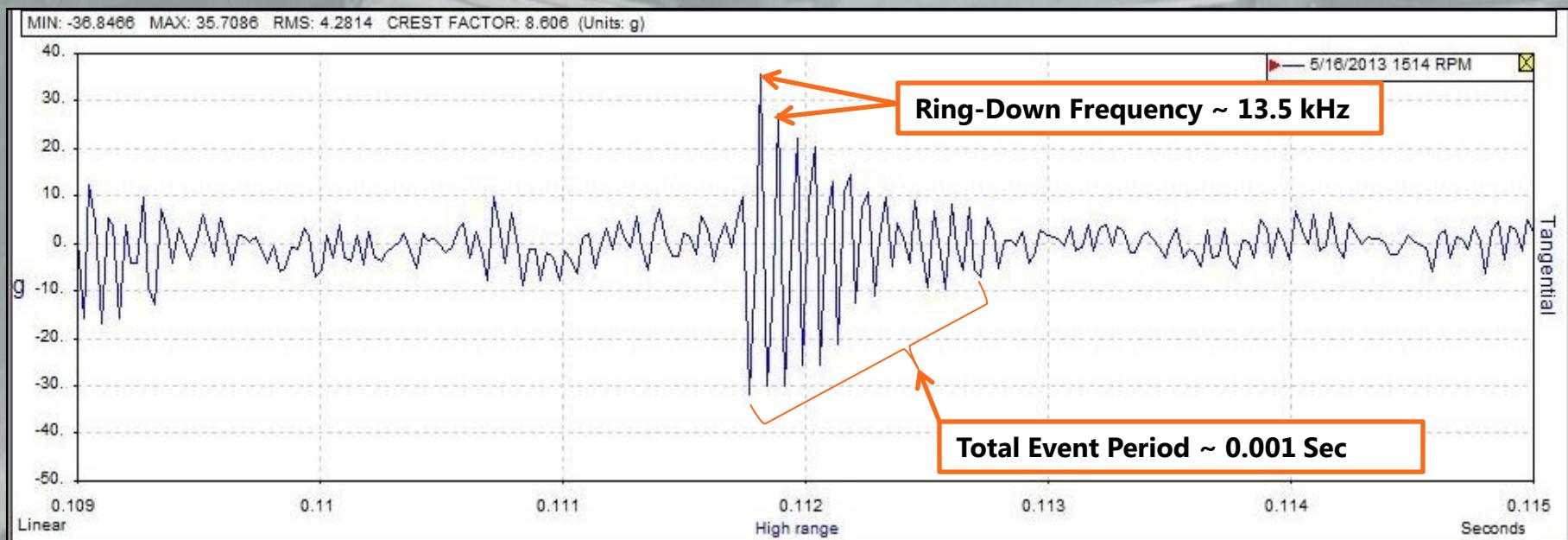


Distinguishing an Impact

Single Impact Illustration in Time Waveform

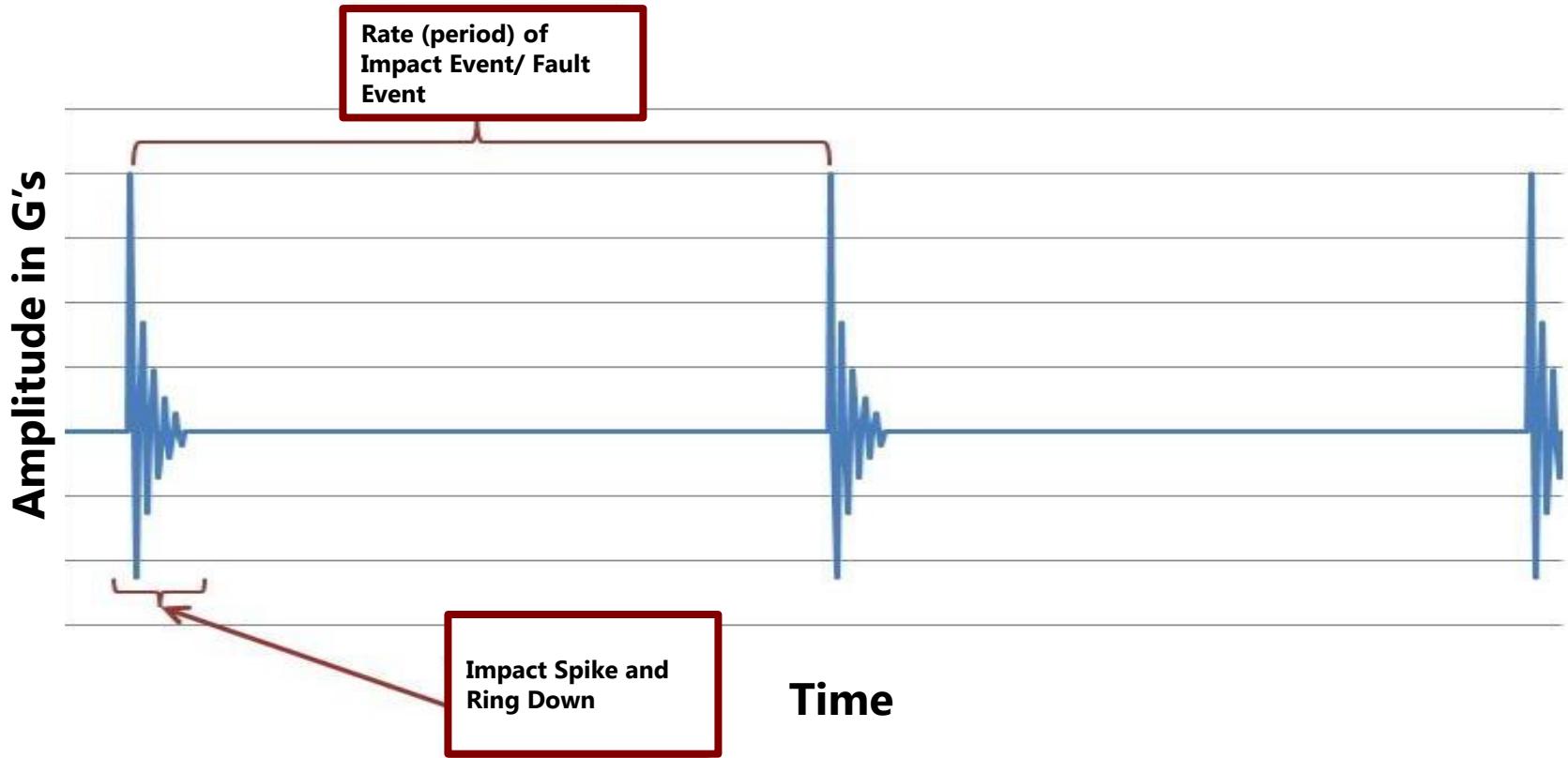


Example: Single Impact Event

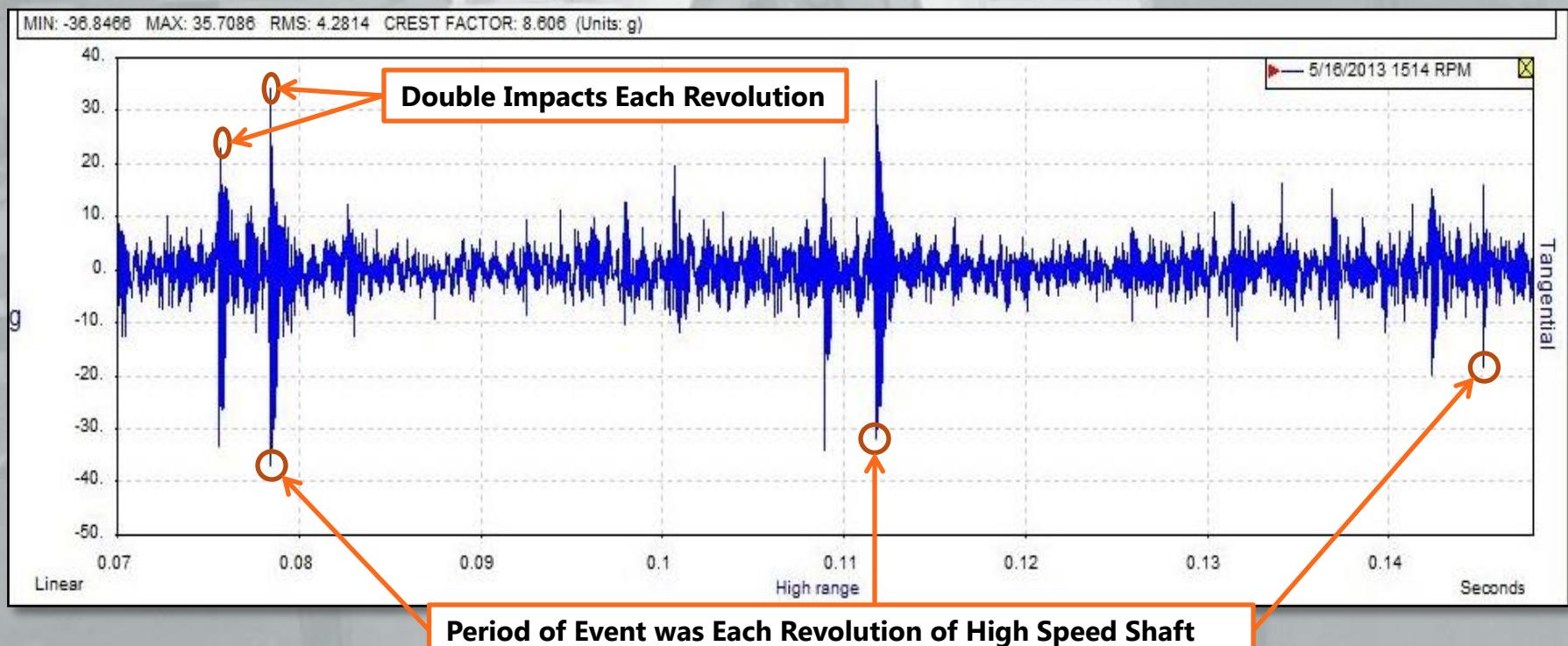


Periodic Impact Spikes

Impact Illustration in Time Waveform



Example: Periodic Impact Events





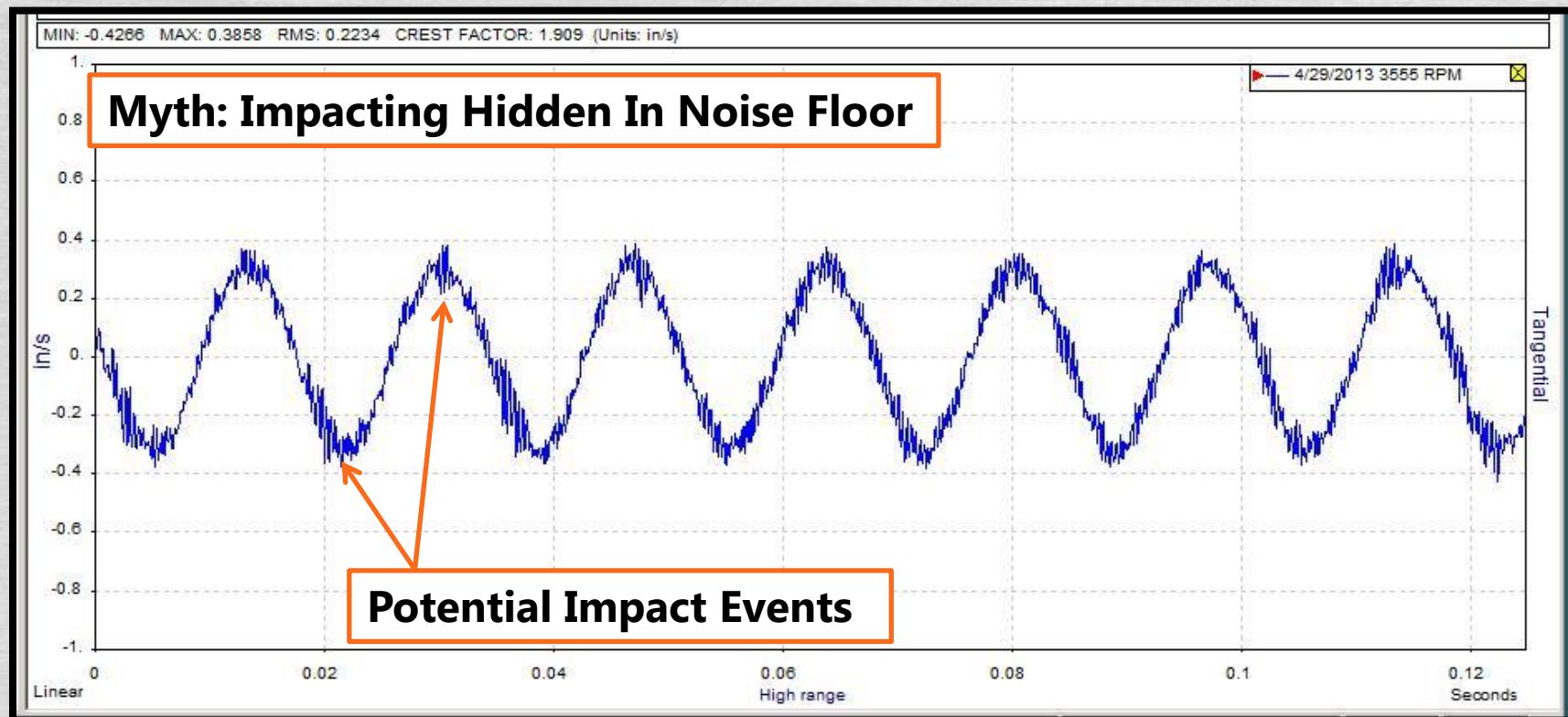
Bearing Impact Faults are Difficult to Detect Because They Produce “Tiny” Signals That Are Hidden in the Noise Floor.

Not True!

What We've Been Told

Impacting Amplitude Example - Low Impacting

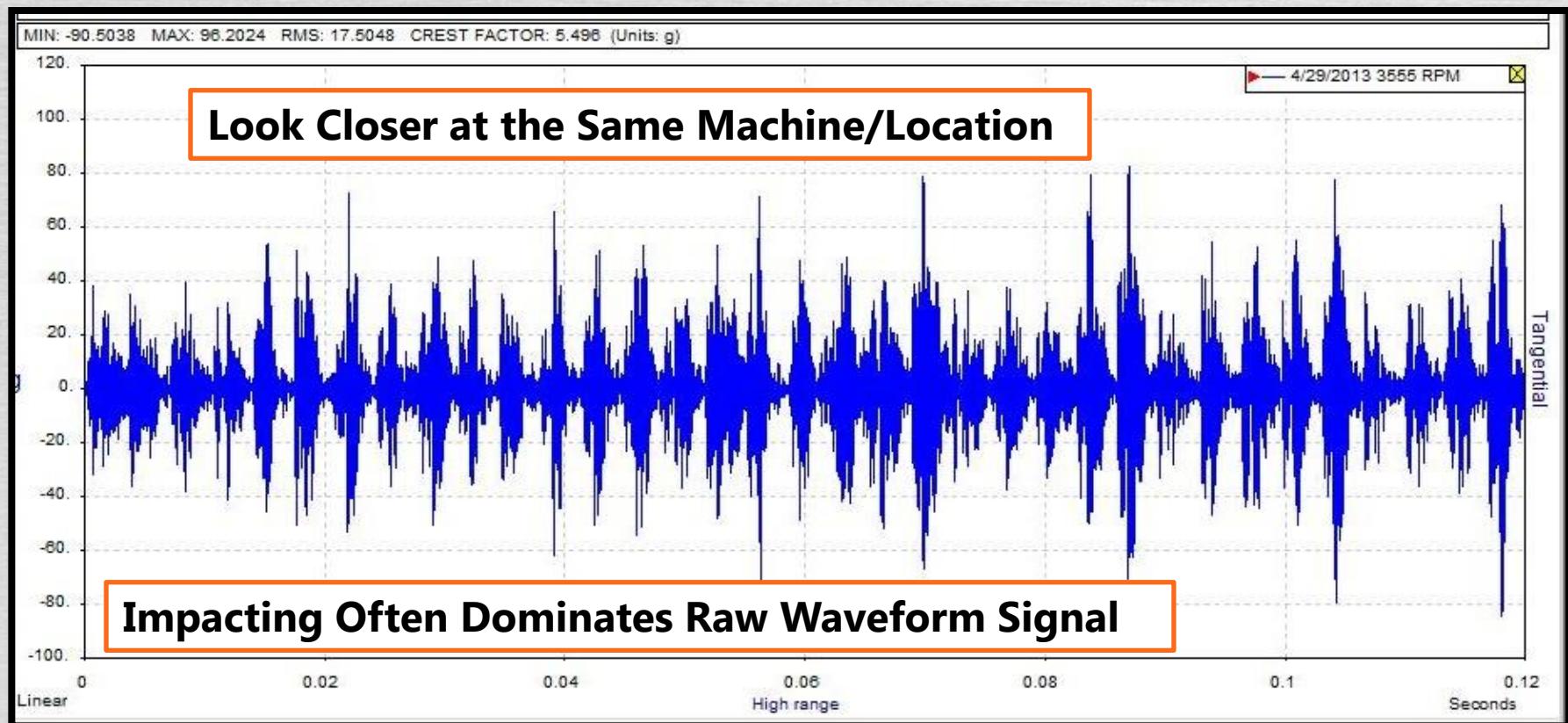
- Fmax at 6000Hz and Integrated



The Reality

Impacting Amplitude Example >180 g

- Fmax at 16,000Hz non-integrated



Why is it Difficult to Detect?

- Requires Very High Sampling Rate
 - Fmax 16,000hz Or Greater
- Requires Long Sampling Times To Provide Adequate Low Frequency Resolution
 - A Sample Time Long Enough To Capture 15 Shaft Revolutions Is Suggested
- Results In Extremely Large Data Set

Why is it Difficult to Detect?



Slow Speed Machine Example

Machine Requiring
Lowest Resolvable
Frequency
of 60 CPM

Typical:

- Fmax – 250Hz
- #Lines - 800
- Resulting Minimum
Resolvable Frequency
= 0.94 Hz

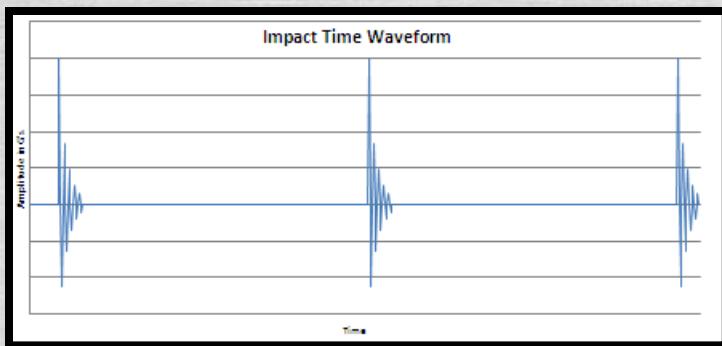
To Match Resolution
at Required
High Sample Rate

Capture Impacts:

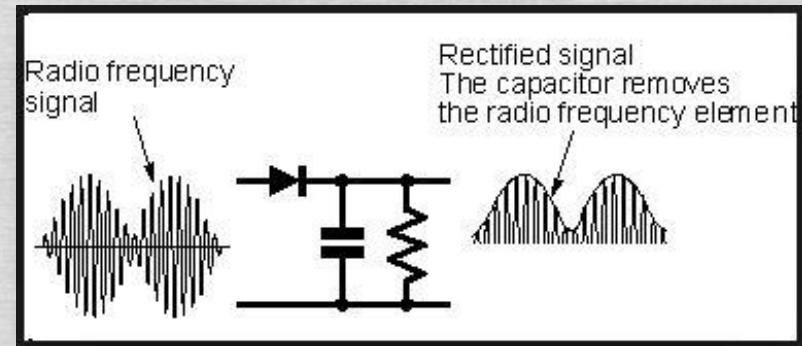
- Fmax - 16,000Hz
- #Lines – 51,200
- Resulting Minimum
Resolvable Frequency
= 0.94 Hz

Legacy Demodulation

- Impact Signals Have Similar Characteristics To Amplitude Modulated Radio Signals
- Amplitude Demodulation Techniques Were Adapted As Bearing Detection Method

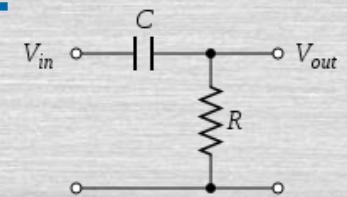


≈

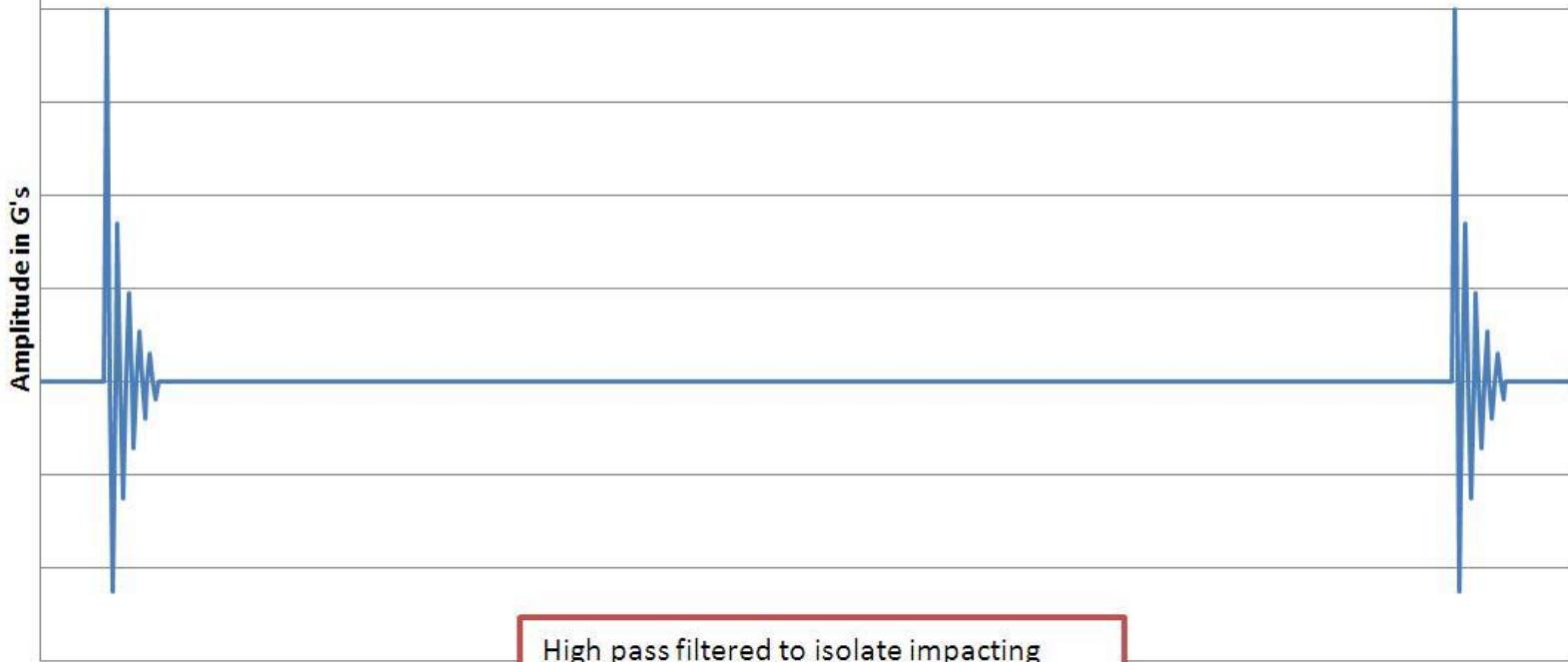


Legacy Demodulation – 1

Signal High Pass Filtered

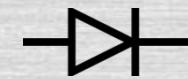


Legacy Demodulation Example in Time Waveform

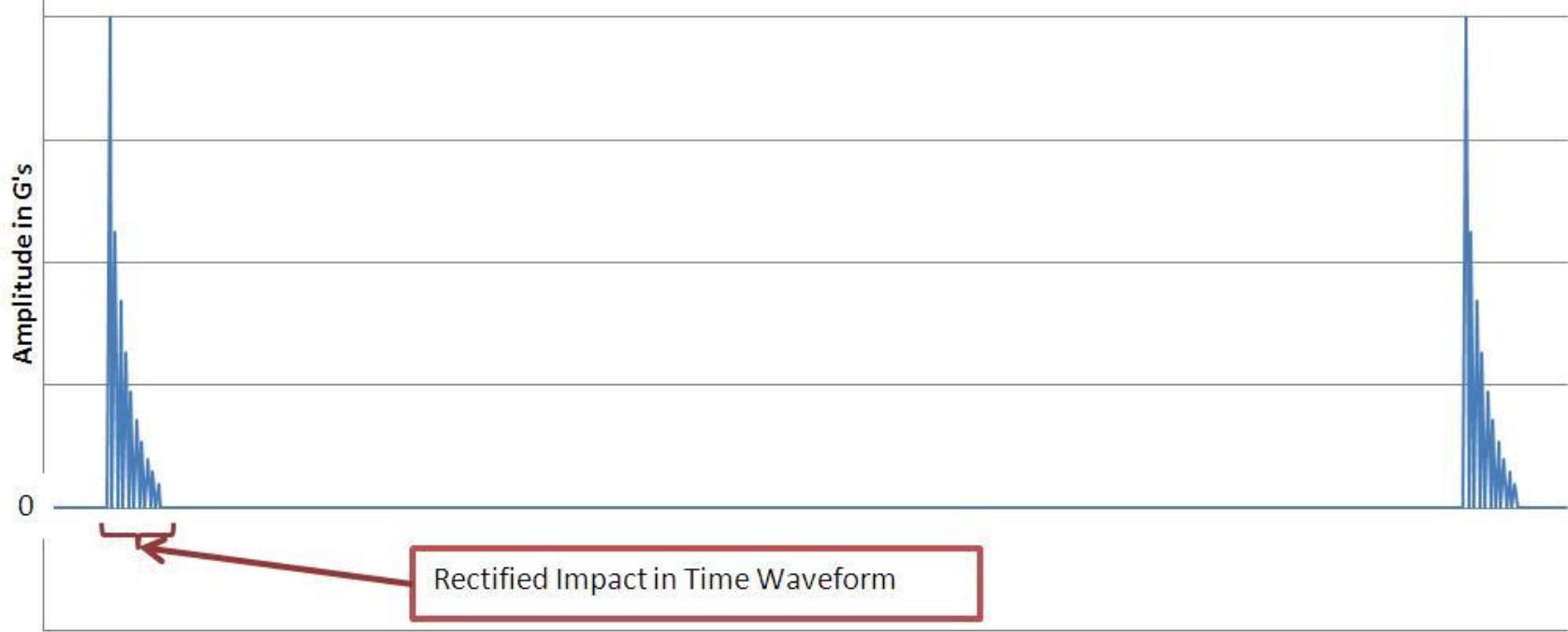


Legacy Demodulation – 2

Force All Peaks to be Positive

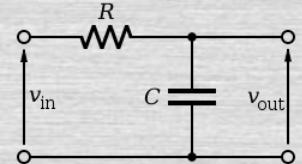


Legacy Demodulation Example in Time Waveform



Legacy Demodulation – 3

Signal Low Pass Filtered (Enveloped)

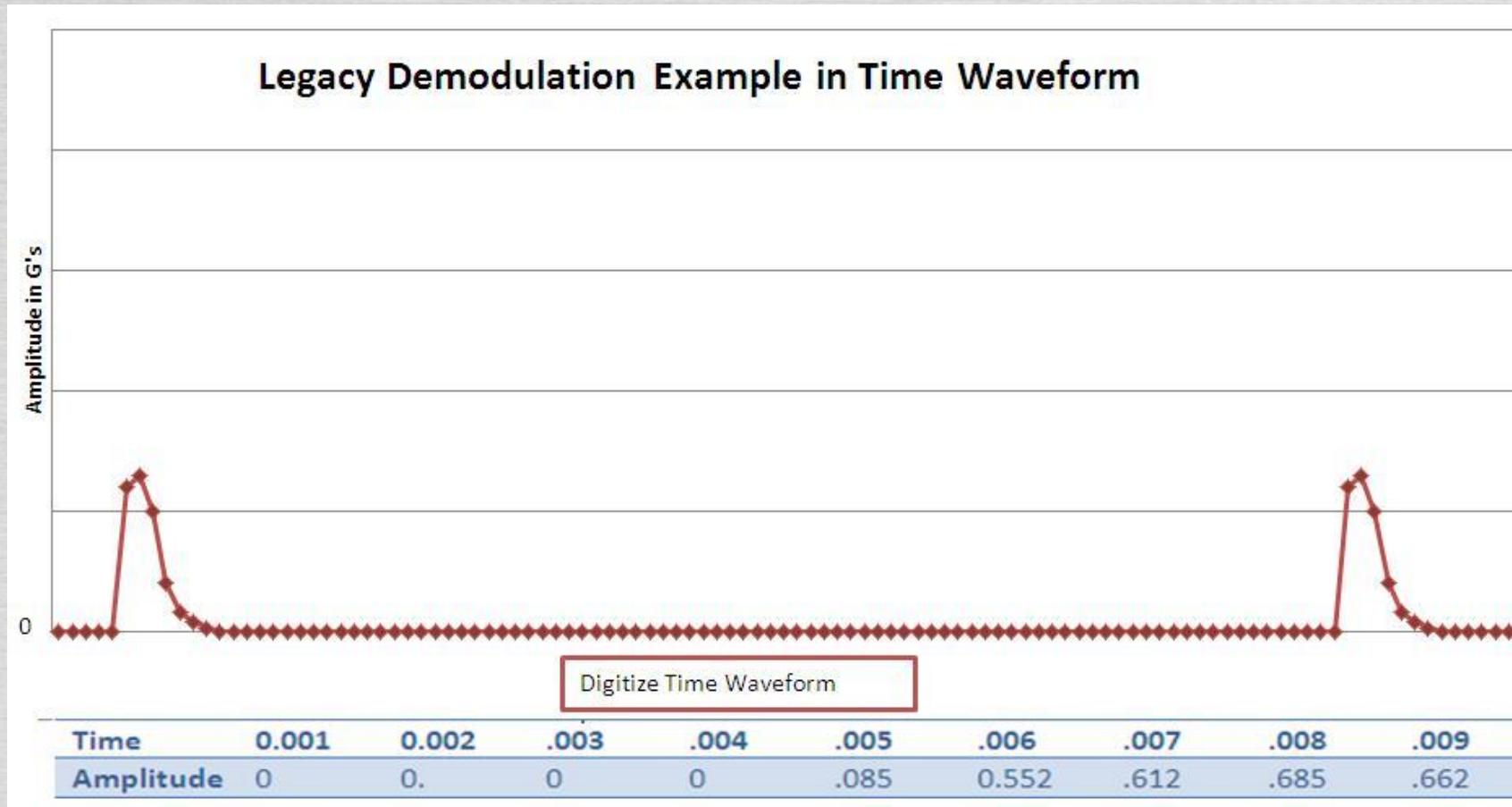


Legacy Demodulation Example in Time Waveform



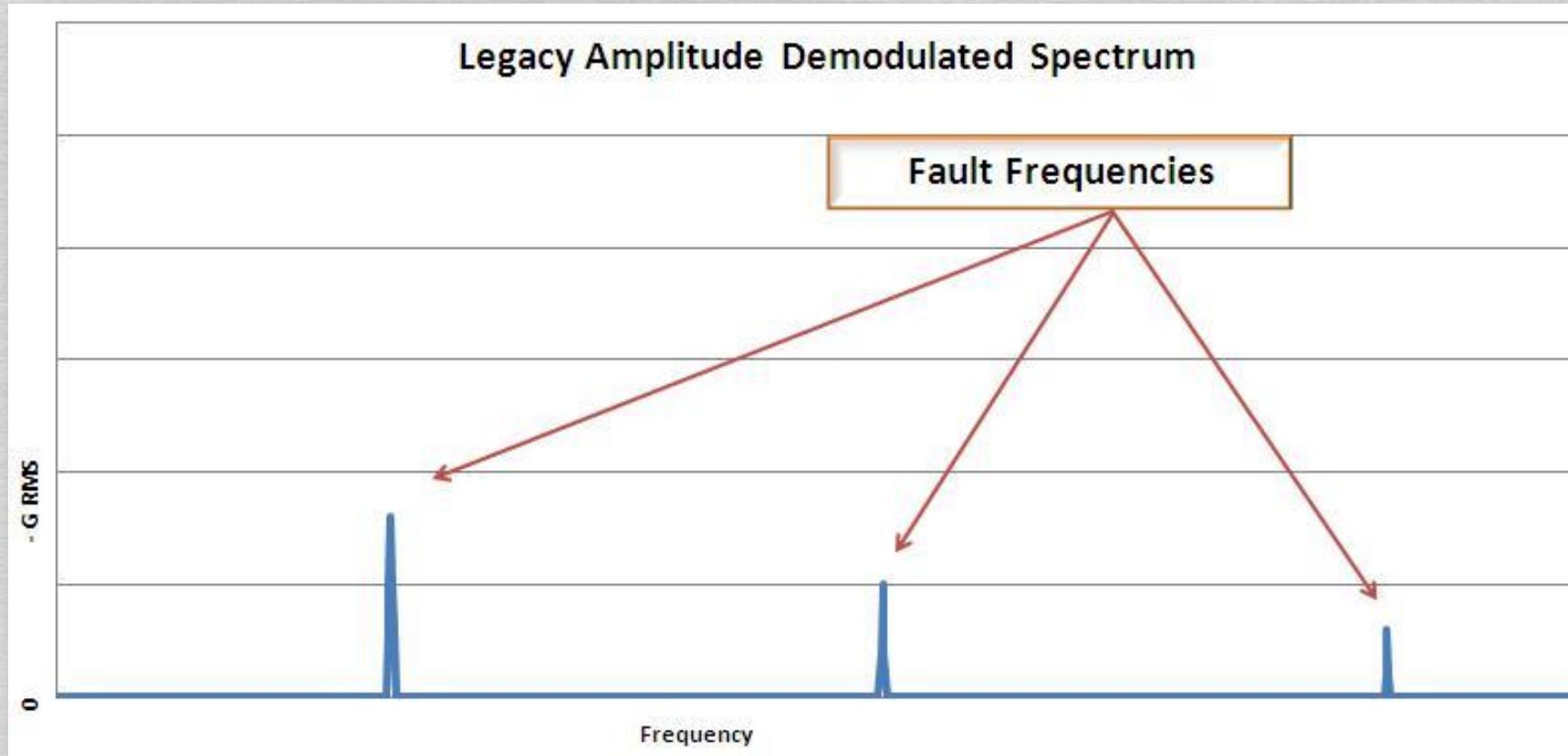
Legacy Demodulation – 4

Pass Waveform Through A/D Converter



Legacy Demodulation – 5

FFT Process – Generate Spectrum



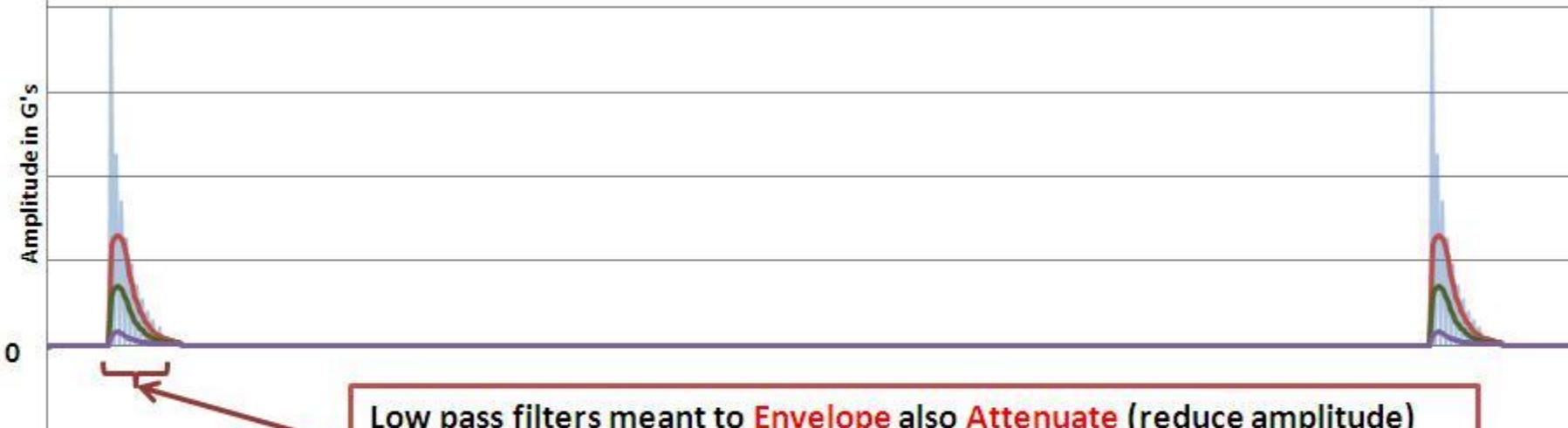
Legacy Demodulation and Slow Speed Machines



Enveloping Flaw

Low Pass Filter is Actually Instrument Anti-Aliasing Filters

Illustration of Various Anti-Aliasing Filter effects on Legacy Demodulation



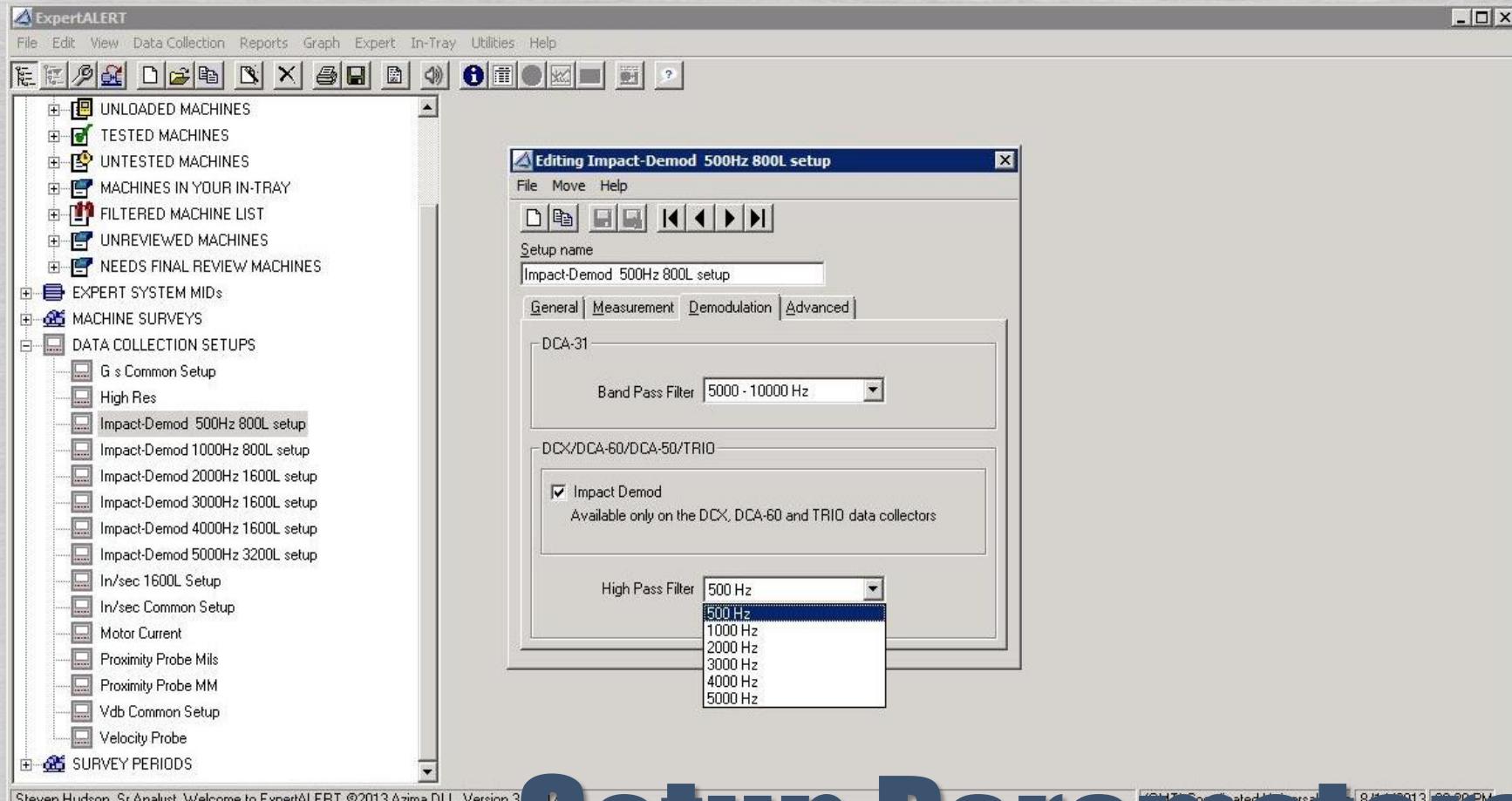
Low pass filters meant to **Envelope** also **Attenuate** (reduce amplitude) the signal. *Filter setting depends on final selected Fmax.*

Note: Impact signals will be lost entirely if their event period does not meet Nyquist criterion of the final Fmax

Solution: Impact Demod

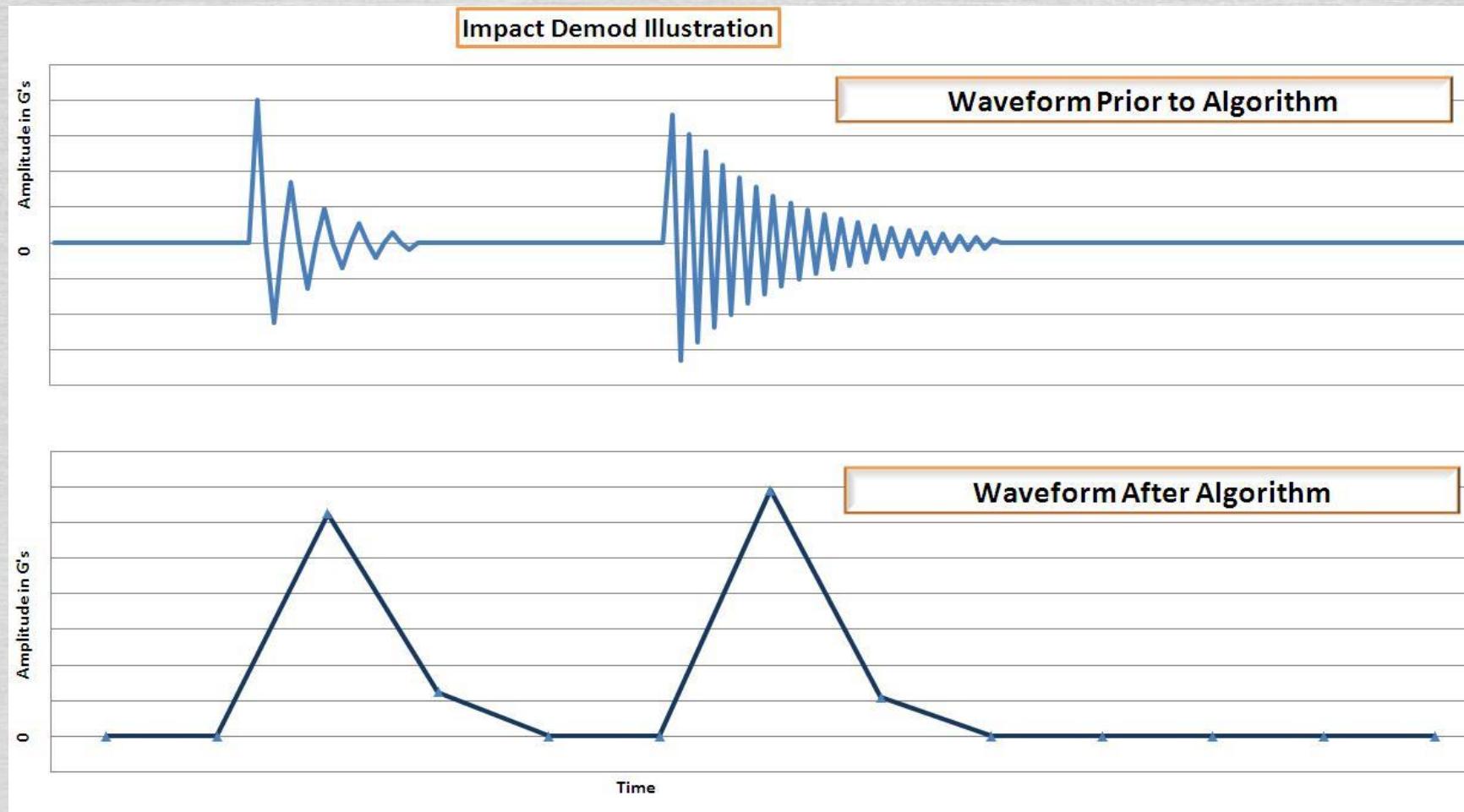


Impact Demod

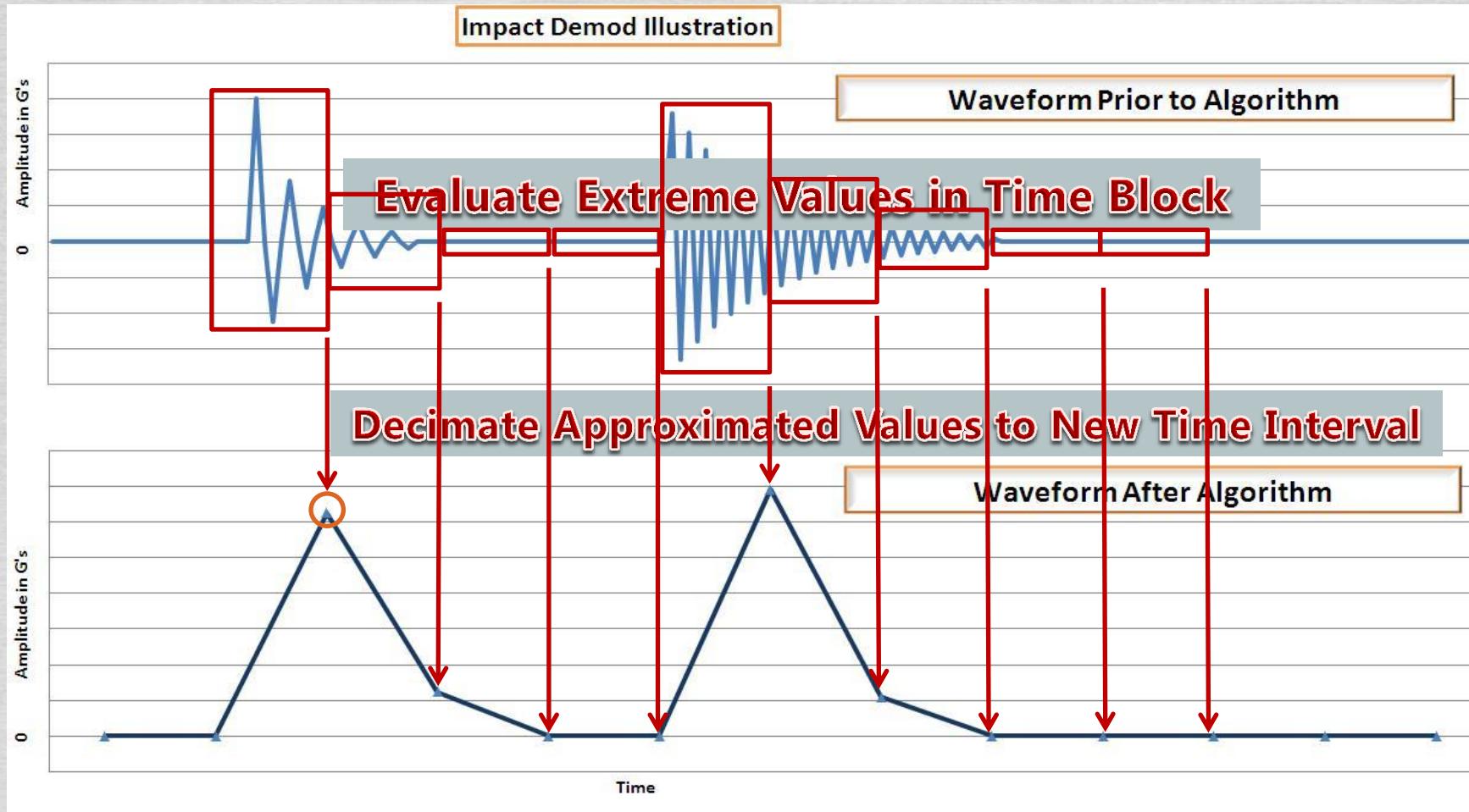


Setup Parameters

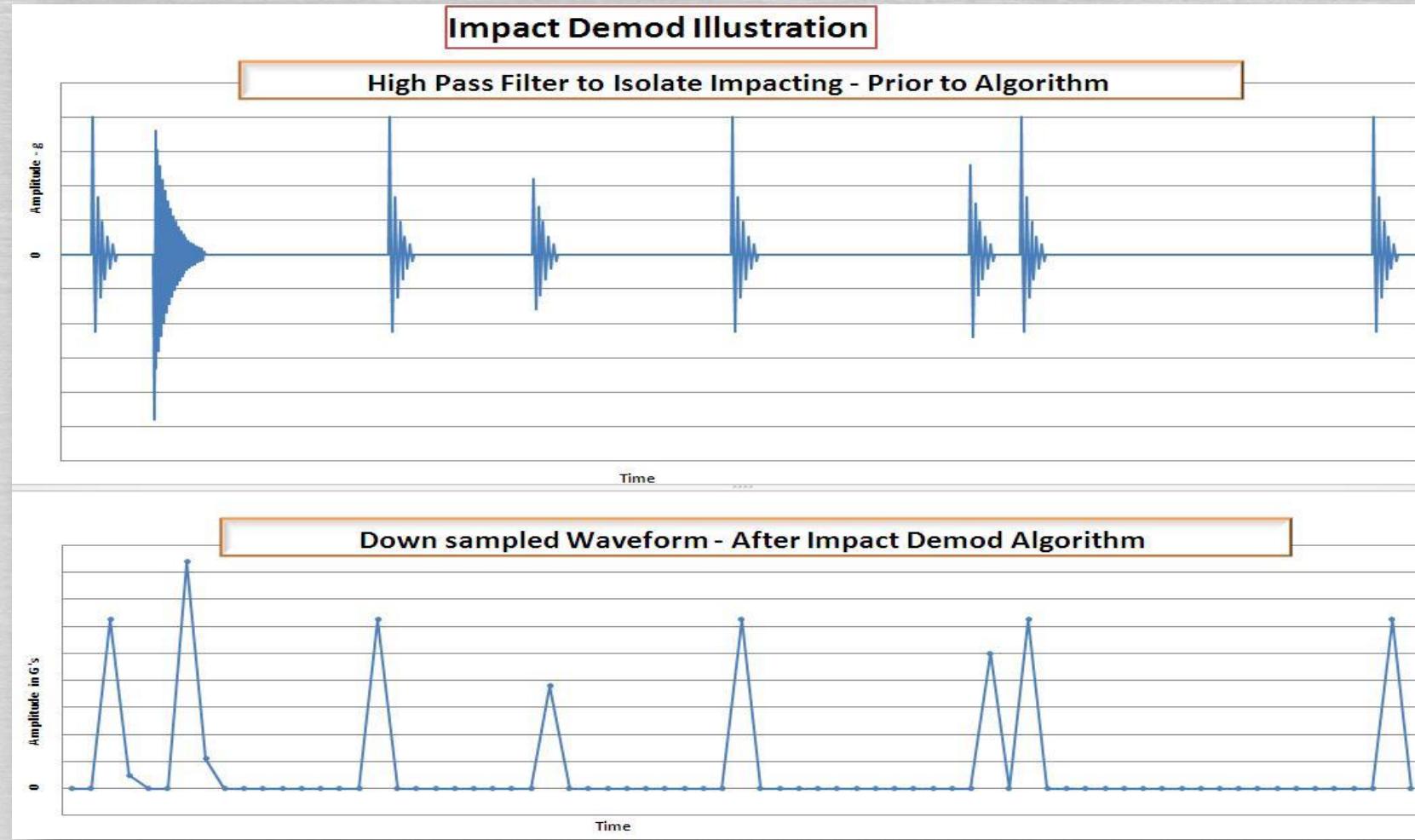
Impact Demod



Impact Demod

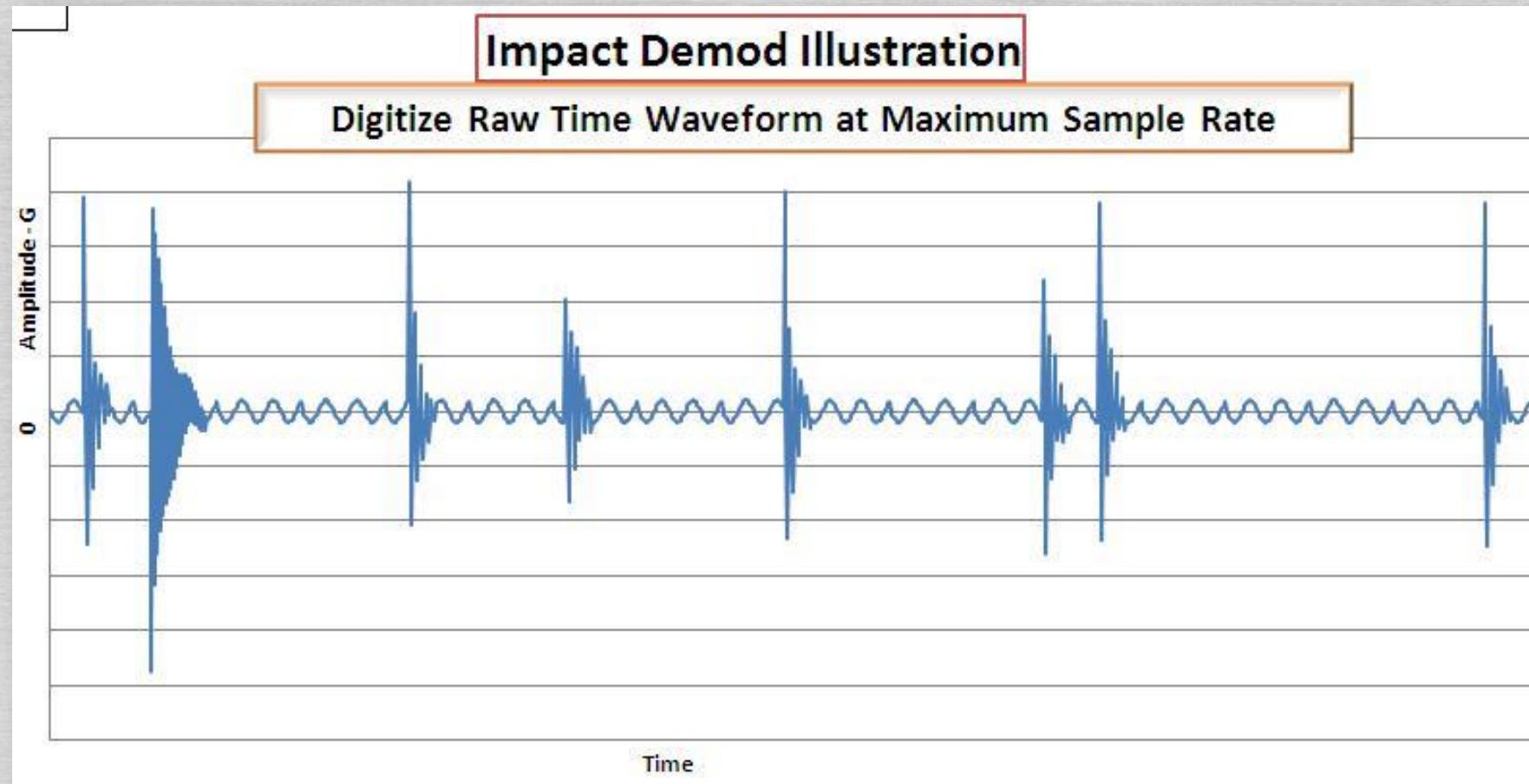


Impact Demod



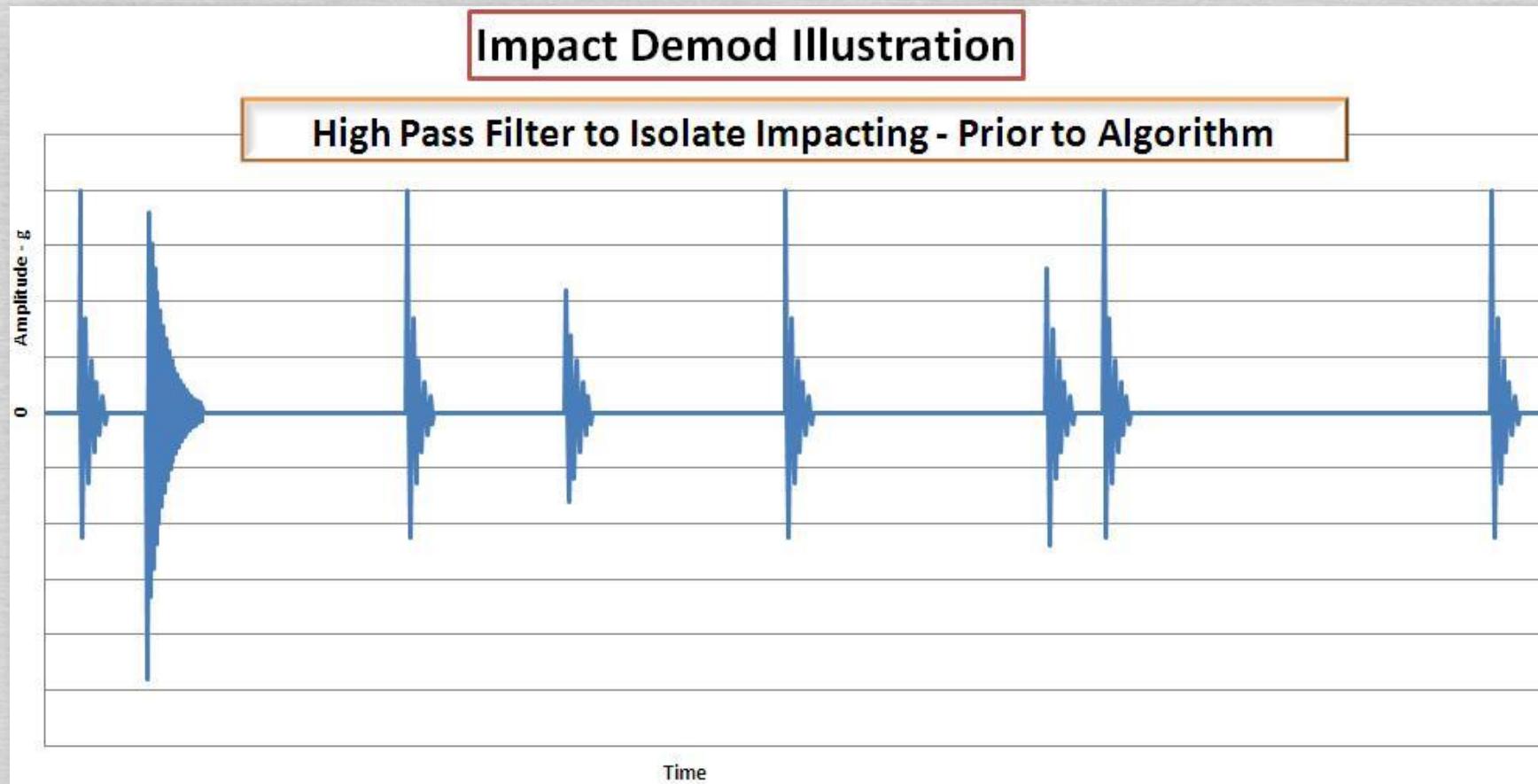
Impact Demod - Step 1

Digitize Acceleration Data



Impact Demod - Step 2

High Pass Filtering

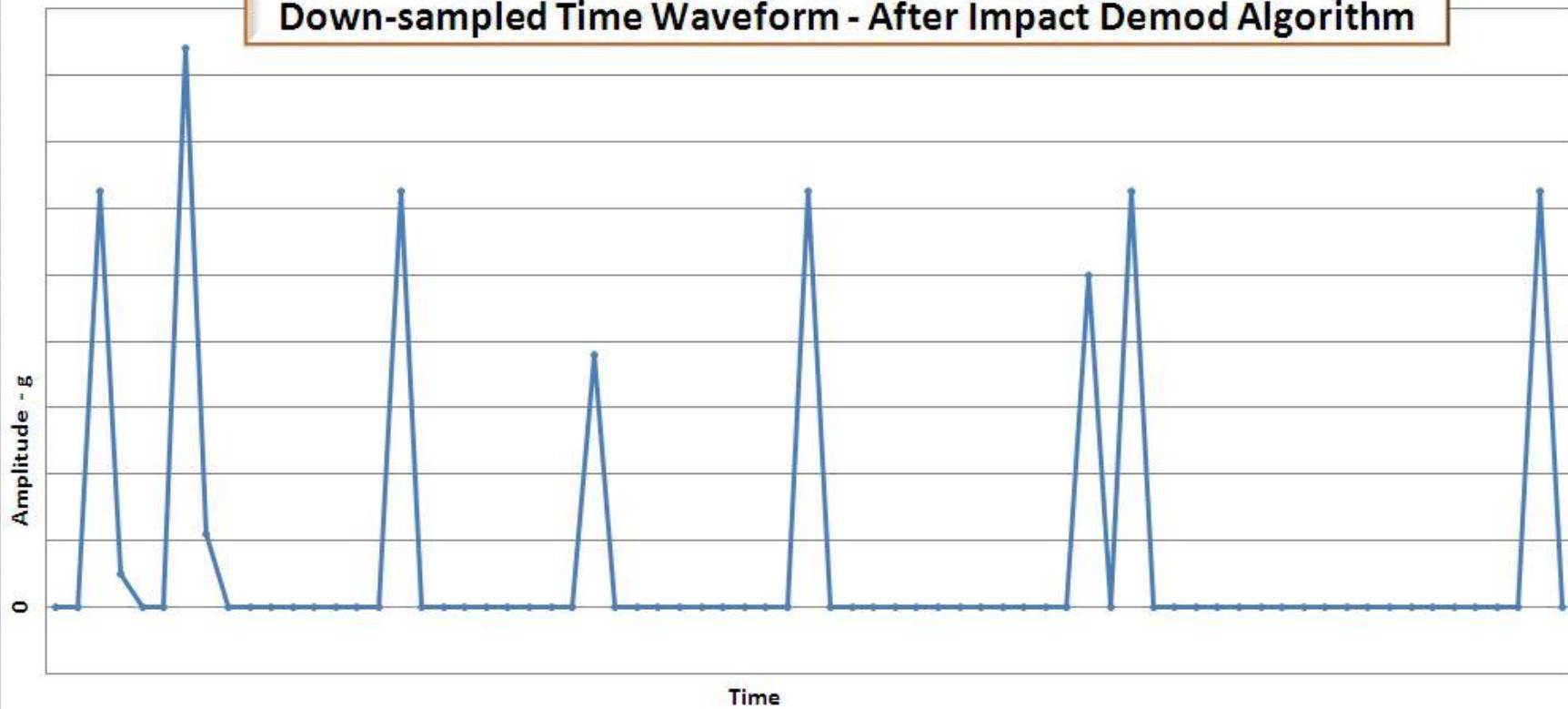


Impact Demod - Step 3

Run Impact Demod Alogrithm

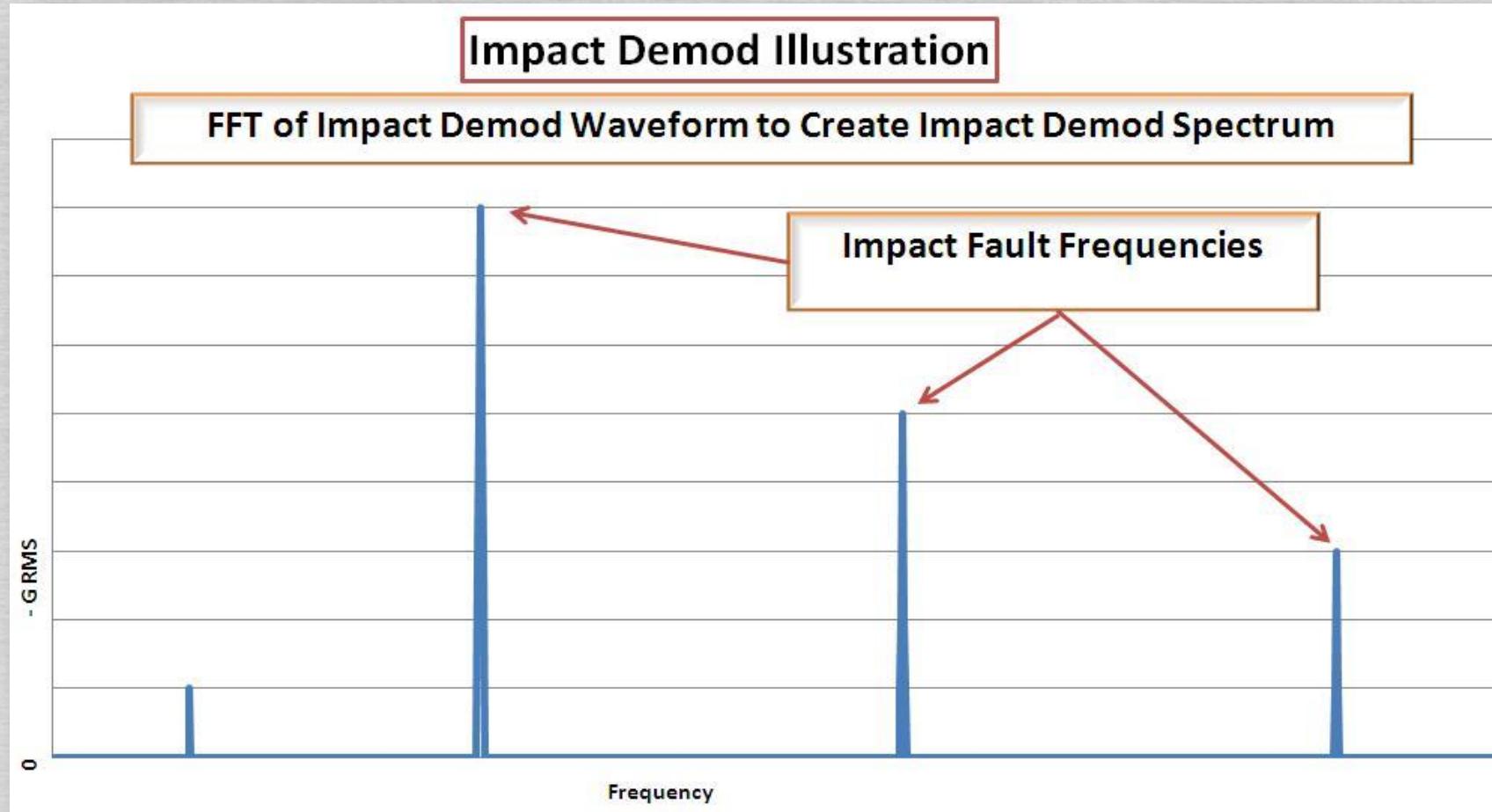
Impact Demod Illustration

Down-sampled Time Waveform - After Impact Demod Algorithm



Impact Demod - Step 4

FFT Process – Generate Impact Demod Spectrum



Impact Demod

- Advantages
 - No Low-pass filter attenuation
 - Retains maximum waveform amplitude
Regardless of final Fmax chosen
 - Simplified filter selection
 - Does not rely on knowing resonance peak

Impact Demod

Setup Tips

- Use units of acceleration
- Attempt to capture at least 15 shaft revolutions in time waveform
- Only one average is recommended
- Use lowest available filter that does not overlap desired Fmax
- Use in-line axis if triaxial sensor

Impact Demod

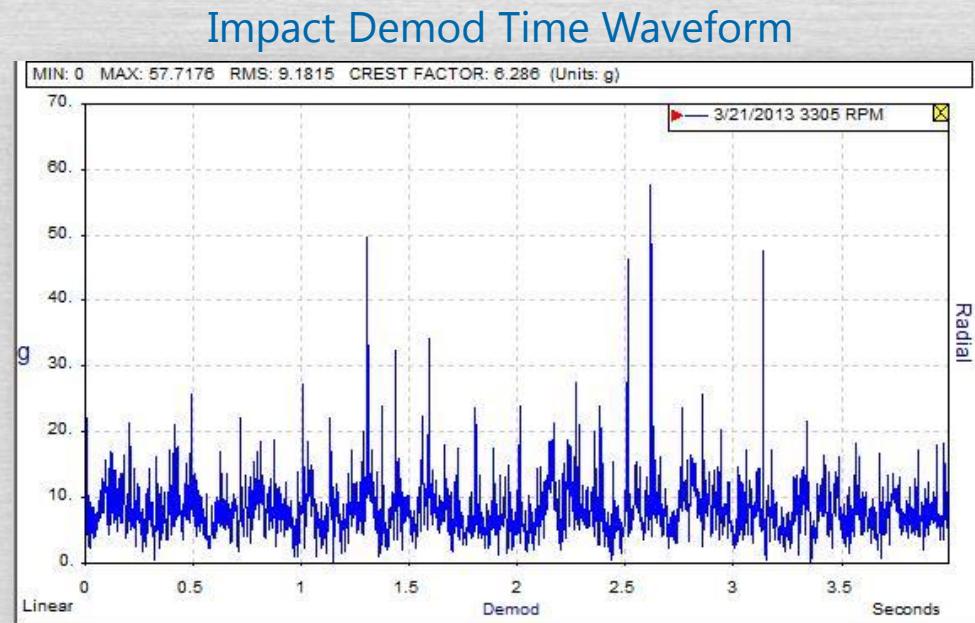
Analysis Tips

- Review the time waveform first
- Maximum values determine severity
- Compare to other like machines
- Determine if waveform content appears Random or periodic (Repetitive Pattern)
- Identify any harmonic sets in spectrum

Impact Demod

Analysis Tips (continued)

- Random impacting indicates
 - Metal to metal friction
 - Pump cavitation

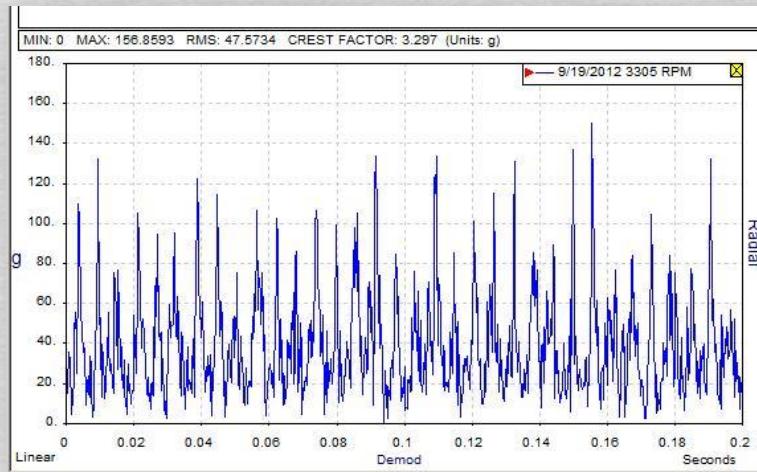


Impact Demod

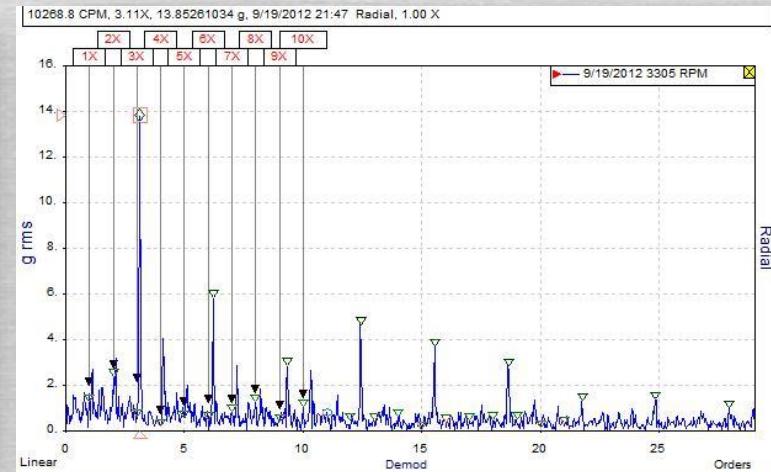
Analysis Tips (continued)

- Periodic Impacting
 - Impact rate indicates faulty component
 - Review spectrum to determine fault frequency

Impact Demod Time Waveform



Impact Demod Spectrum

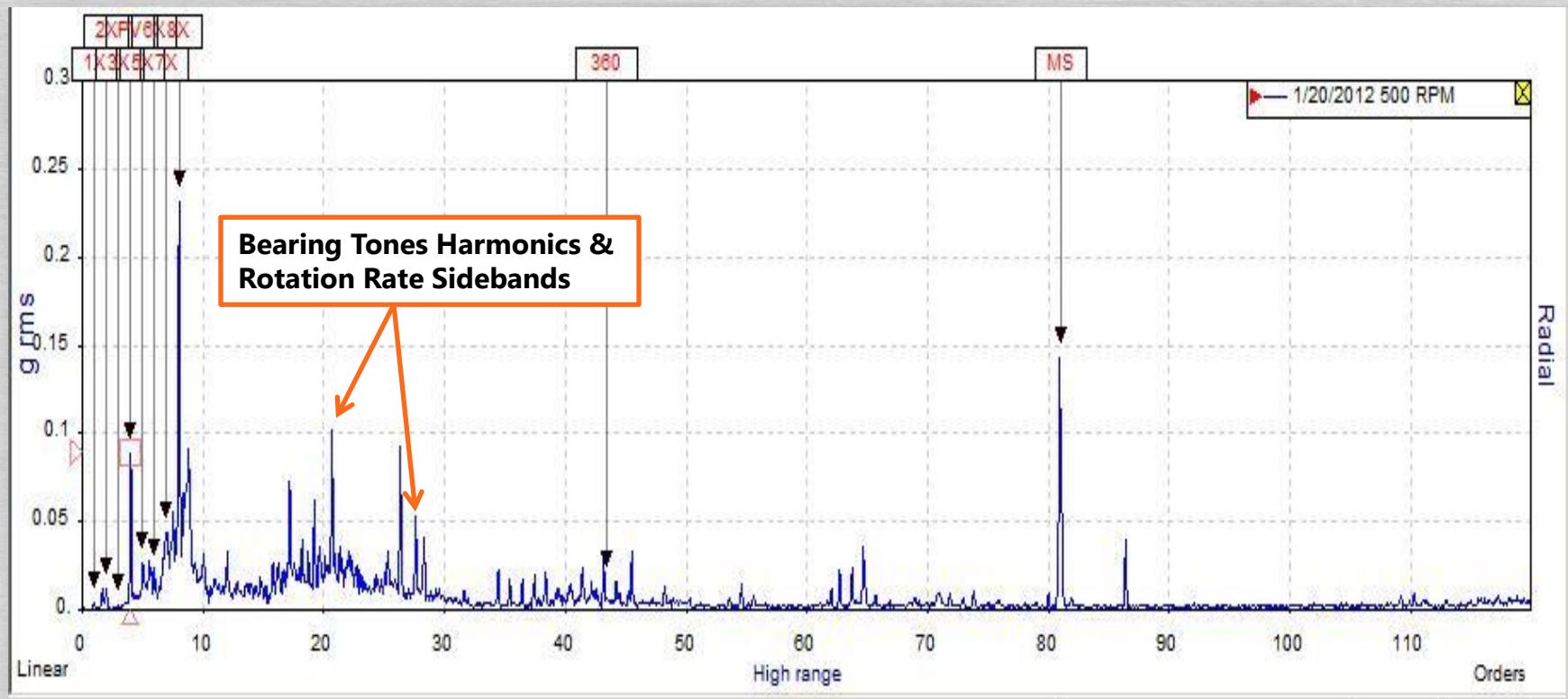


Impact Demod: *In Practice*



Slow Speed - Motor Coupled End

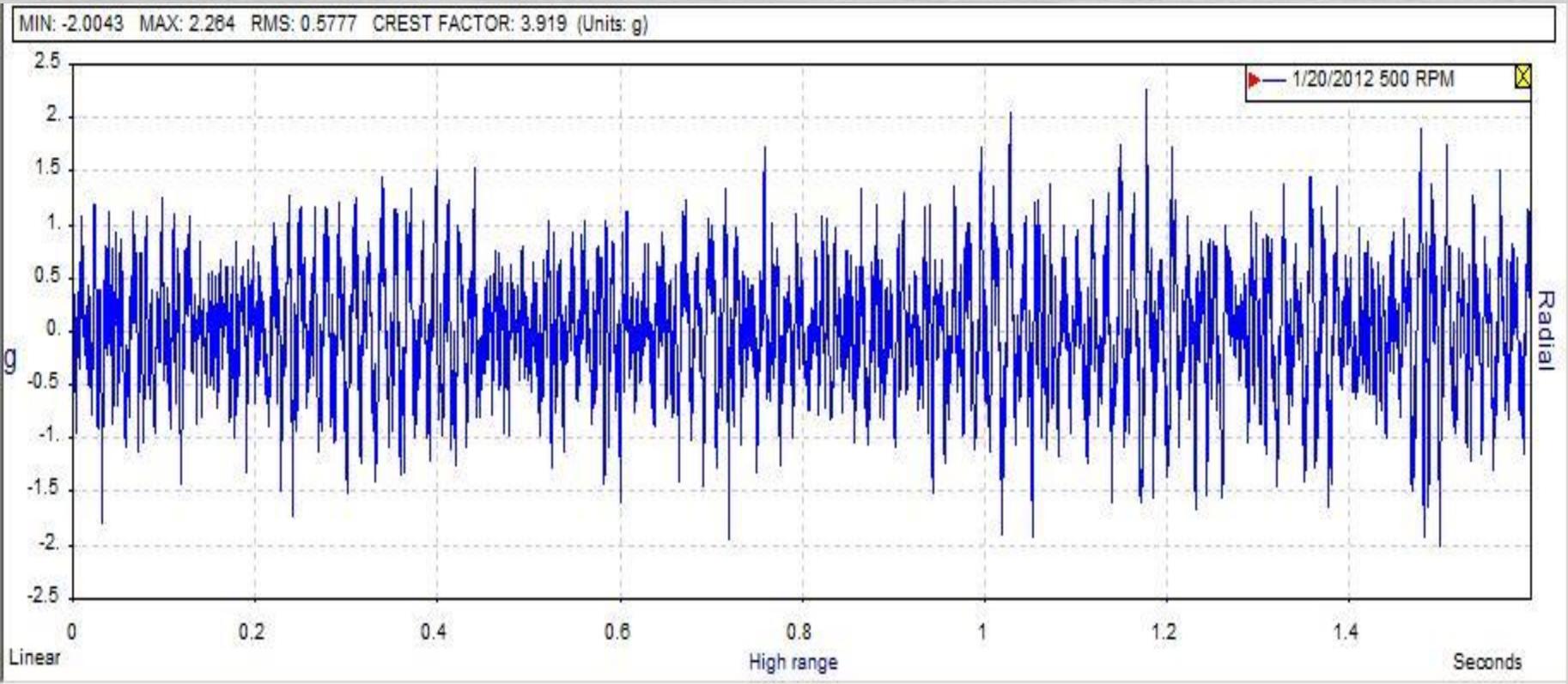
Standard High Range Spectrum



Indication of some HF bearing noise

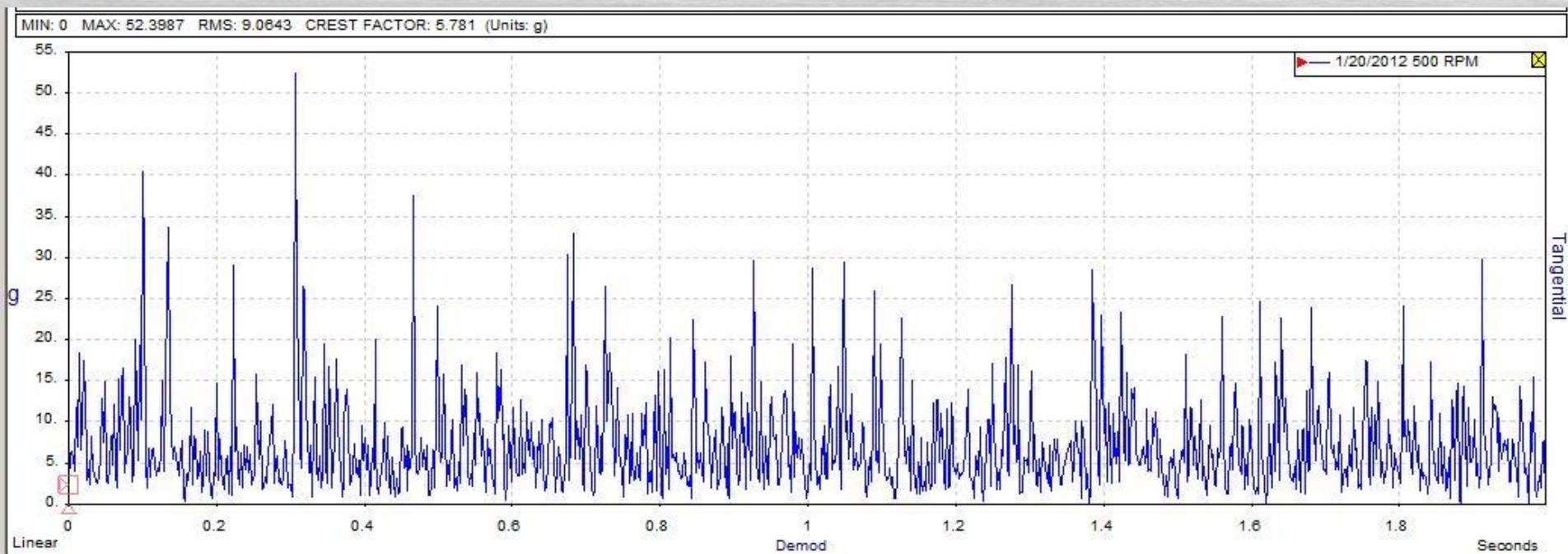
Slow Speed - Motor Coupled End

High Range Time Waveform



Slow Speed - Motor Coupled End

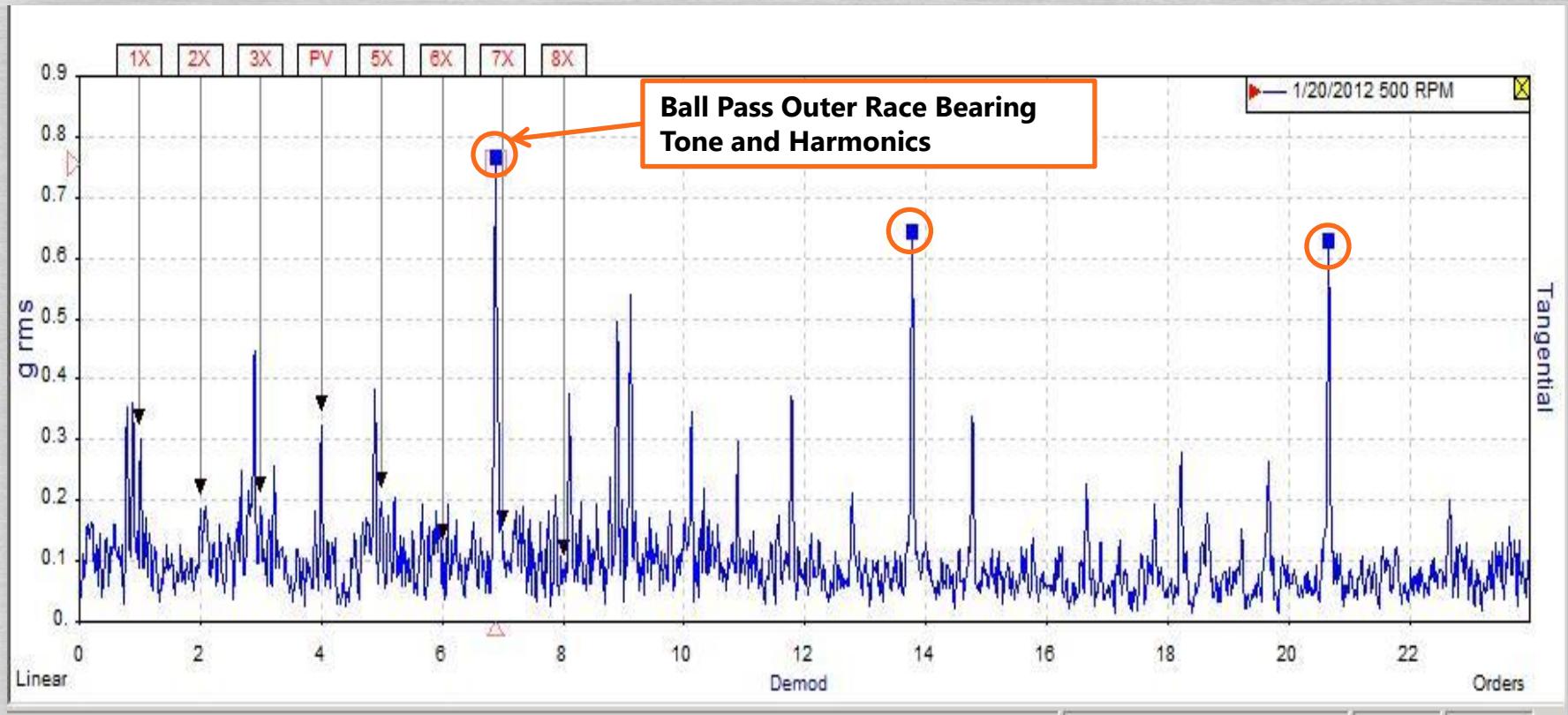
Impact Demod Waveform



Indication of serious impacting – 52g

Slow Speed - Motor Coupled End

Impact Demod Spectra



Indication of periodic content at $6.9xM$

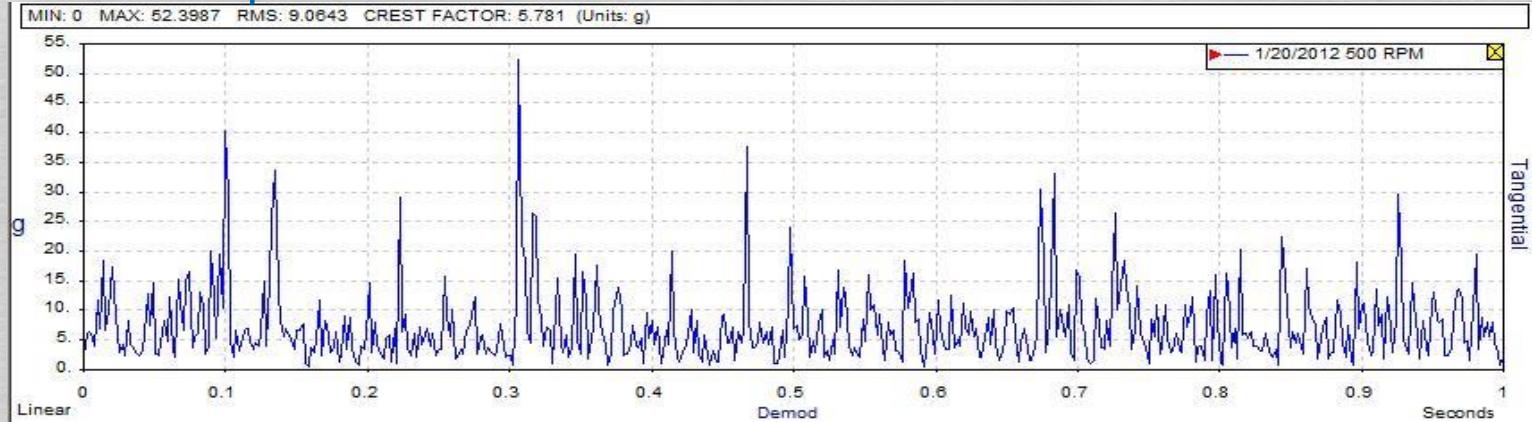
What Was Found



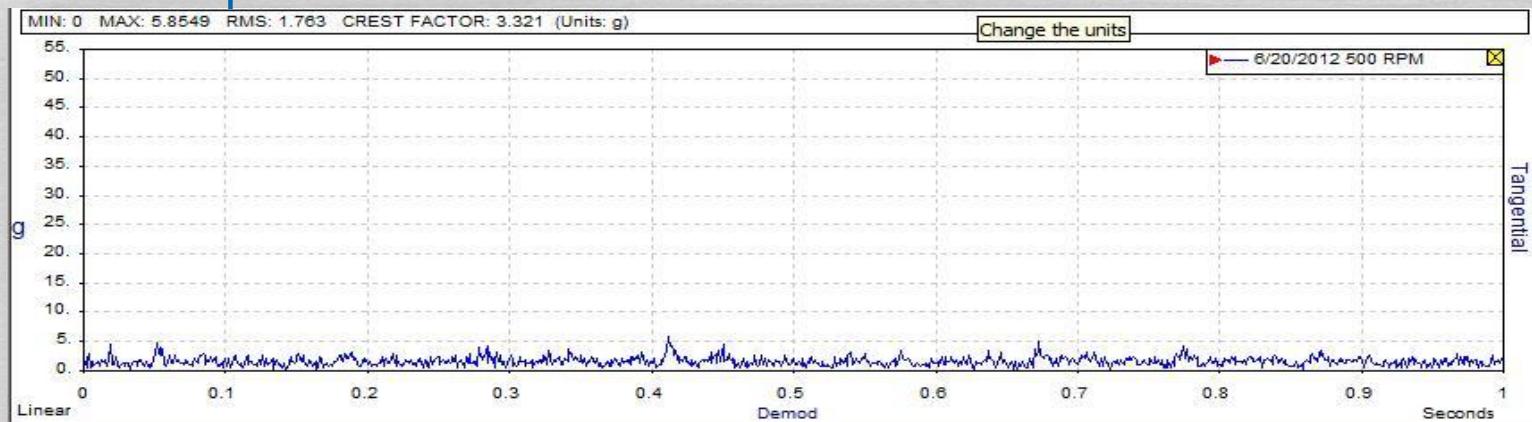
Motor Coupled End

Impact Demod Time Waveform - Comparison

Before Repair



After Repair





Impact Demod DCUOD





Steven Hudson

Senior Analyst

Azima DLI

www.azimadli.com

THANK YOU!





Az AZIMA DLI hivatalos magyarországi képviseletét a Delta-3N Kft. látja el. Delta-3N Kft. 7030 Paks, Jedlik Á. u. 2. www.delta3n.hu